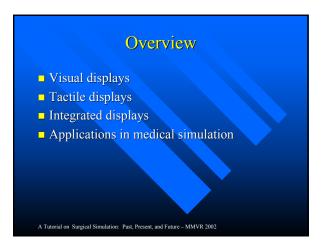
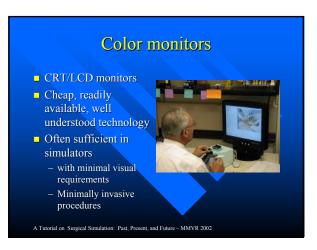
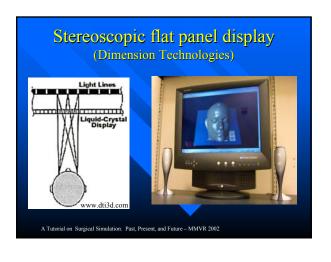
Visual and tactile displays Alan Liu aliu@simcen.usuhs.mil Surgical Simulation Laboratory National Capital Area Medical Simulation Center Uniformed Services University http://simcen.usuhs.mil/mmvr2002

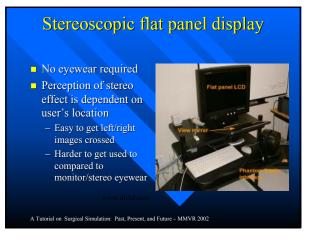


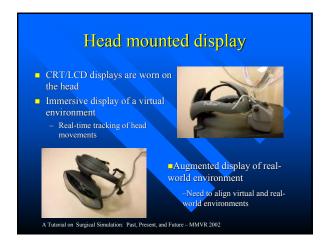








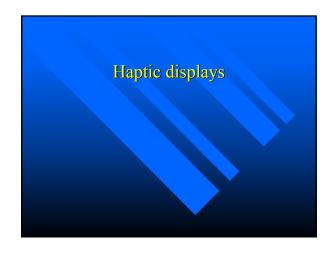












Definitions

- Tactile (touch) feedback: sensed by receptors close to the skin (high bandwidth)
- Force feedback: sensed by receptors placed deeper in the body (low bandwidth)
- Haptic feedback: technically same as tactile feedback, but often extended to include both tactile and force feedback as in haptics
- Source: Force and Touch Feedback For Virtual Reality, Burdea

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Phantom (Sensable Technologies)

- Sensors report movement in 6 degrees of freedom (dof)
- 3 dof force feedback
- Force feedback loop must be updated rapidly (1kHz refresh rate or better)
- Widely used for in surgical simulation research

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Virtual Laparoscopic Interface/ Laparoscopic Impulse Engine

- Interface device for simulated laparoscopic procedures
- Haptic and non-haptic version



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Haptic Catheter/Needle Insertion Simulator



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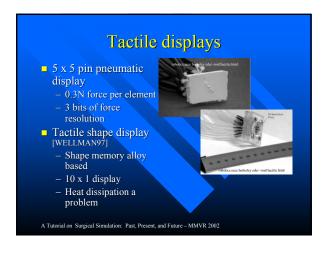
Endoscopy Simulator

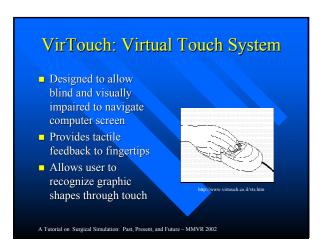
- Flexible scope-like interface
- Computer generated imagery of anatomical structures
- Different procedures can be simulated
 - Bronchoscopy
 - Endoscopy

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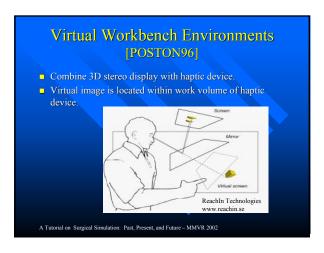
















- PHANTOM force
- feedback - Stereo monitor
- Semi-transparent mirror
- Swiss company: Reachin Technologies



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i.e.Med Reality Sculptor

- Components
 - Input device (such as PHANTOM or tracking system)
 - Windows PC with OpenGL graphics card
 - Mirror and stand
 - TDI software development kit



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Resources

- Head mounted displays
- Tracking
- Stereoscopic displays

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